Phone: (845) 500-6332 | Email: KyleBThompson0616@gmail.com | LinkedIn

EDUCATION

Massachusetts Institute of Technology

Candidate for Bachelor of Science in Mechanical Engineering Minor in Design and Concentration in Economics

• Relevant Coursework: State-Space Control; Design & Manufacturing I: Autonomous Machines; Thermal-Fluids Engineering I & II; Mechanics & Materials; Fundamentals of Programming; Dynamics I & II; Computational Thinking & Data Science; Numerical Computation in MATLAB; Engineering Systems Design

GPA:4.7/5.0

• Relevant Course Projects: Active Gimbal Control; Small Radar System (SAR and Doppler); Magnetic Levitation: Electromagnetic Control; 2WD 2.s007 Robot

WORK EXPERIENCE

MIT Dynamics and Controls II

Lab Assistant and Grader

Cambridge, MA January 2022-Present

Cambridge, MA

2019-2023

Aid MIT's Dynamics and Controls II lab professors in prepping materials and set ups for lab, assist • students with completion of objectives, and help grade assessments

Jaros Baum & Bolles

Engineering Intern

Evaluated thermal loads for various space states, calculated pressure drops in proposed systems, and developed an in-house calculator to evaluate building infiltration

PROJECTS

Self-Balancing Robot Control

MIT Dynamics and Controls

September-December 2021 Developed stabilization feedback control for self-balancing Segway for long term stability and path following with PD, PID, and State Space controllers

Autonomous Underwater Vehicle

- MIT Engineering Systems Design
 - Redesigned and manufactured weight-shifting mechanism of AUV for pitch and roll control Purchasing Lead: purchased and organized supply logistics, coordinated with outside manufacturers •

Built an Operational Nuclear Fusor MIT NSE

Using the resources and tools provided by MIT, I was able to construct a working Farnsworth Fusor and • operate it in the presence of Deuterium once under vacuum

MIT PokerBots

Top 20 Finalist and Top 10 Freshmen Teams

- A computerized poker tournament in which teams program a completely autonomous pokerbot to compete against other teams in one month; with the challenge of a random permutation of card values
- Utilized Baye's Theorem to generate a more consistent list of valid permutations after showdown

SKILLS

Programming: MATLAB; Python; ARDUINO; Git; Simulink and Simscape; Image Processing; ROS Design and Fabrication: CAD Experience; Solid Works; CNC Mill; CNC Lathe; Waterjet; 3D Printing

LEADERHIP

• Engineering Systems Design Purchase Lead; Dormitory Chair; Social Chair at Sigma Alpha Epsilon

New York, NY June 2021-July 2021

Cambridge, MA

Cambridge, MA

September-December 2021

Cambridge, MA January-February 2020

Cambridge, MA January-February 2020